

### **Amendments to the Specification**

**Please replace the paragraph beginning at page 2, line 23, with the following rewritten paragraph:**

To achieve the above-described object, an aspect of the present invention is directed to a navigation apparatus of guiding a vehicle to a destination. The navigation apparatus comprises a destination setting section of setting a destination in accordance with an input by a driver, a location deriving section of deriving a current location of the vehicle, a path obtaining section of obtaining a path from the current location derived by the location deriving section as a starting point to the destination set by the destination setting section, a data storing section of storing an information set including at least location information for identifying a location of a travel burden point on a road network, link information indicating a road linked to the travel burden point, and a reference hesitation value indicating a degree of a driver's hesitation to go through the travel burden point, and a characteristic value of the driver, a point guidance data generating section of generating point guidance data representing guidance for the travel burden point based on the current location derived by the location deriving section, the path obtained by the path obtaining section, and the information set and the driver characteristic value stored in the data storing section, and an output section of outputting the guidance for the travel burden point in accordance with the point guidance data generated by the point guidance data generating section. The point guidance data generating section compares a reference hesitation value contained in the information set stored in the data storing section with a driver characteristic value, and based on a result of the comparison, generates point guidance data.

**Please delete the paragraph at page 4, lines 14-16.**

**Please replace the paragraph beginning at page 5, line 2, with the following rewritten paragraph:**

A second aspect of the present invention is directed to a guidance method which is performed in a navigation apparatus and is for guiding a vehicle to a destination. The navigation

apparatus comprises a data storing section of storing an information set including at least location information for identifying a location of a travel burden point on a road network, link information indicating a road linked to the travel burden point, and a reference hesitation value indicating a degree of a driver's hesitation to go through the travel burden point, and a characteristic value of the driver. The method comprises a destination setting step of setting a destination in accordance with an input by a driver, a location deriving step of deriving a current location of the vehicle, a path obtaining step of obtaining a path from the current location derived by the location deriving step as a starting point to the destination set by the destination setting step, a point guidance data generating step of generating point guidance data representing guidance for the travel burden point based on the current location derived by the location deriving step, the path obtained by the path obtaining step, and the information set and the driver characteristic value stored in the data storing section, and an output step of outputting the guidance for the travel burden point in accordance with the point guidance data generated by the point guidance data generating step. The point guidance data generating step compares a reference hesitation value contained in the information set stored in the data storing section with a driver characteristic value, and based on a result of the comparison, generates point guidance data.

**Please replace the paragraph beginning at page 6, line 10, with the following rewritten paragraph:**

The computer program comprises a destination setting step of setting a destination in accordance with an input by a driver, a location deriving step of deriving a current location of the vehicle, a path obtaining step of obtaining a path from the current location derived by the location deriving step as a starting point to the destination set by the destination setting step, a point guidance data generating step of generating point guidance data representing guidance for the travel burden point based on the current location derived by the location deriving step, the path obtained by the path obtaining step, and the information set and the driver characteristic value stored in the data storing section, and an output step of outputting the guidance for the travel burden point in accordance with the point guidance data generated by the point guidance

data generating step. The point guidance data generating step compares a reference hesitation value contained in the information set stored in the data storing section with a driver characteristic value, and based on a result of the comparison, generates point guidance data.

**Please insert the paragraphs at page 6, after line 25, as follows:**

As an illustrative example, the computer program is stored in a recording medium.

A fourth aspect of the present invention is directed to a navigation apparatus of guiding a vehicle to a destination. The navigation apparatus comprises a destination setting section of setting a destination in accordance with an input by a driver, a location deriving section of deriving a current location of the vehicle, a path obtaining section of obtaining a path from the current location derived by the location deriving section as a starting point to the destination set by the destination setting section, a calculation section of calculating a reference hesitation value indicating a degree of a driver's hesitation to go through a travel burden point on a road network after the path obtaining section obtains the path, a data storing section of storing an information set including at least the reference hesitation value calculated by the calculation section of the travel burden point, location information for identifying a location of the travel burden point, and link information indicating a road linked to the travel burden point, and a characteristic value of the driver, a point guidance data generating section of generating point guidance data representing guidance for the travel burden point based on the current location derived by the location deriving section, the path obtained by the path obtaining section, and the information set and the driver characteristic value stored in the data storing section, and an output section of outputting the guidance for the travel burden point in accordance with the point guidance data generated by the point guidance data generating section.

A fifth aspect of the present invention is directed to a guidance method which is performed in a navigation apparatus and is for guiding a vehicle to a destination. The navigation apparatus comprises a data storing section of storing at least location information for identifying a location of a travel burden point on a road network, link information indicating a road linked to the travel burden point, and a characteristic value of the driver. The method comprises a destination setting step of setting a destination in accordance with an input by a driver, a location

deriving step of deriving a current location of the vehicle, a path obtaining step of obtaining a path from the current location derived by the location deriving step as a starting point to the destination set by the destination setting step, a calculation step of calculating a reference hesitation value indicating a degree of a driver's hesitation to go through a travel burden point on a road network after the path obtaining section obtains the path, a data storing step of storing at least the reference hesitation value of the travel burden point calculated by the calculation step, a point guidance data generating step of generating point guidance data representing guidance for the travel burden point based on the current location derived by the location deriving step, the path obtained by the path obtaining step, the reference hesitation value stored by the data storing step, and location information for identifying a location of a travel burden point on a road network, link information indicating a road linked to a travel burden point, and a characteristic value of a driver, which are stored in the data storing section, and an output step of outputting the guidance for the travel burden point in accordance with the point guidance data generated by the point guidance data generating step.

A sixth aspect of the present invention is directed to a computer program which is performed in a navigation apparatus and is for guiding a vehicle to a destination. The navigation apparatus comprises a data storing section of storing at least location information for identifying a location of a travel burden point on a road network, link information indicating a road linked to the travel burden point, and a characteristic value of the driver. The computer program comprises a destination setting step of setting a destination in accordance with an input by a driver, a location deriving step of deriving a current location of the vehicle, a path obtaining step of obtaining a path from the current location derived by the location deriving step as a starting point to the destination set by the destination setting step, a calculation step of calculating a reference hesitation value indicating a degree of a driver's hesitation to go through a travel burden point on a road network after the path obtaining section obtains the path, a data storing step of storing at least the reference hesitation value of the travel burden point calculated by the calculation step, a point guidance data generating step of generating point guidance data representing guidance for the travel burden point based on the current location derived by the location deriving step, the path obtained by the path obtaining step, the reference hesitation value

stored by the data storing step, and location information for identifying a location of a travel burden point on a road network, link information indicating a road linked to a travel burden point, and a characteristic value of a driver, which are stored in the data storing section, and an output step of outputting the guidance for the travel burden point in accordance with the point guidance data generated by the point guidance data generating step.

The computer program is stored in a recording medium.